

# Holistic, Instance-level Human Parsing



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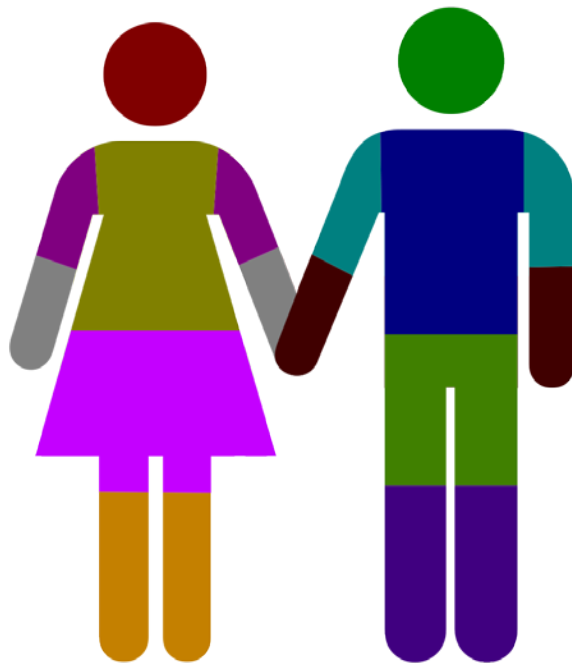
\* Indicates equal contribution by the authors

05 September 2017

# 1. Objective

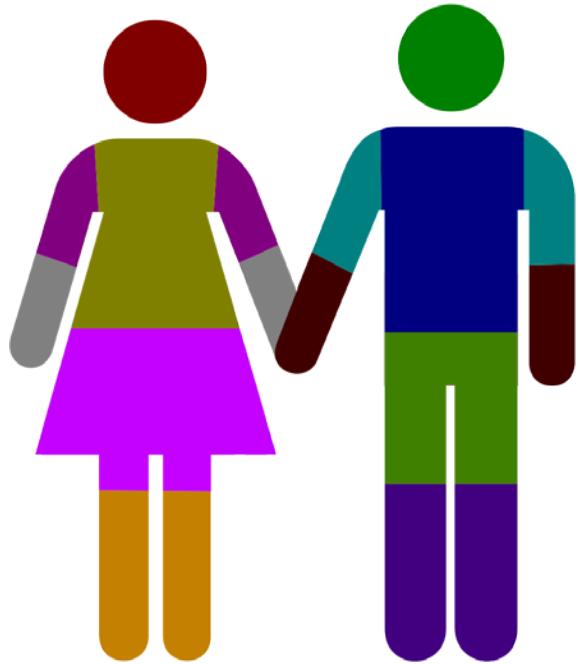


# 1. Objective

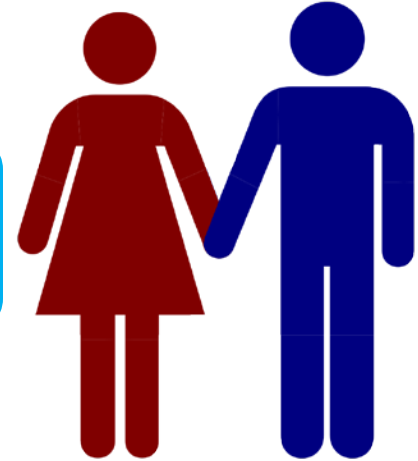


*Instance-aware* body part segmentation of humans

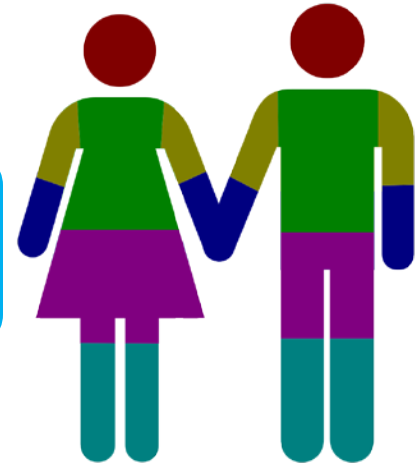
# 1. Objective



*Instance-level human segmentation*



*Category-level body part segmentation*

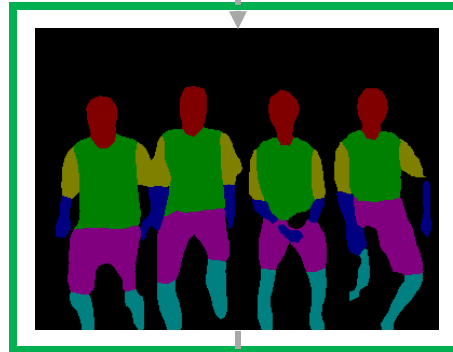


# 2. Methodology

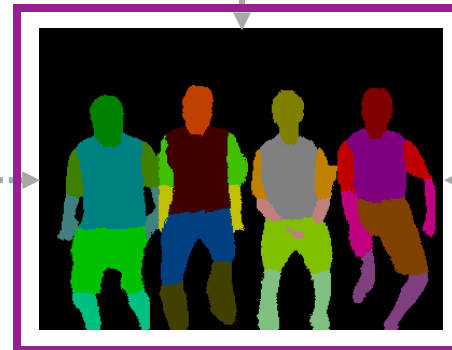
1. Do **category-level body part segmentation**



2. **Detect humans**



3. Use the **instance-level segmentation module** to assign instance labels.



## 2.1 Methodology: Instance-level segmentation module

Instance CRF

$$E(\mathbf{V} = \mathbf{v}) = - \sum_i^N \ln(w_1 \psi_{Box}(v_i) + w_2 \psi_{Global}(v_i) + \varepsilon) + \sum_{i < j}^N \psi_{Pairwise}(v_i, v_j)$$

Where  $\mathbf{V} = \{V_1, V_2, \dots, V_N\}$  is a multinomial variable at all  $N$  pixels,  
 $V_i \in \{1, 2, \dots, D\} \times \{1, 2, \dots, P\} \cup \{0, 0\}$   
 $E(\mathbf{V} = \mathbf{v})$  is the energy of  $\mathbf{V}$  taking a particular value  $\mathbf{v}$

## 2.1.1 Methodology: Box term

- **Input 1:** human detections:
  - scores  $s_i$  and bounding boxes  $B_i$  for  $1 \leq i \leq D$
- **Input 2:** semantic segmentation network output:
  - Feature map  $Q$  with  $P + 1$  channels ( $P = 6$  here)

- **Output:**

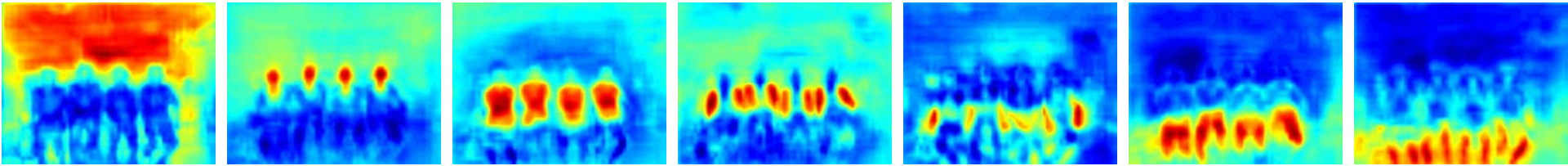
$$\psi_{Box} (V_k = (i, j)) = \begin{cases} s_i Q_k(j), & k \in B_i \\ 0, & k \notin B_i \end{cases}$$

for  $(i, j) \in \{1, 2, \dots, D\} \times \{1, 2, \dots, P\}$

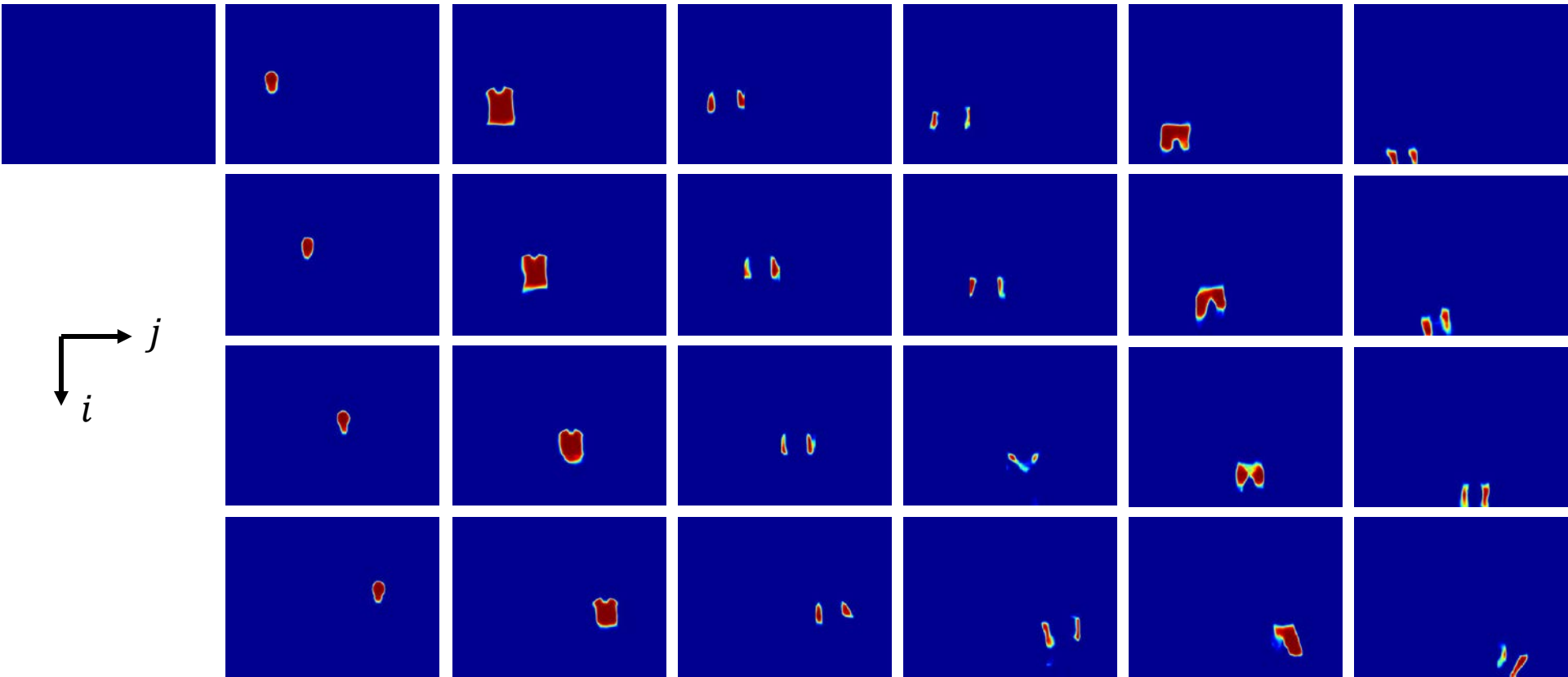
**Input 1:** Human detections



**Input 2:** Semantic body part segmentation probability maps



**Output:** Box terms





## 2.1.2 Methodology: Global term

- **Input:** semantic segmentation network output:
  - Feature map  $Q$  with  $P + 1$  channels ( $P = 6$  here)
- **Output:**

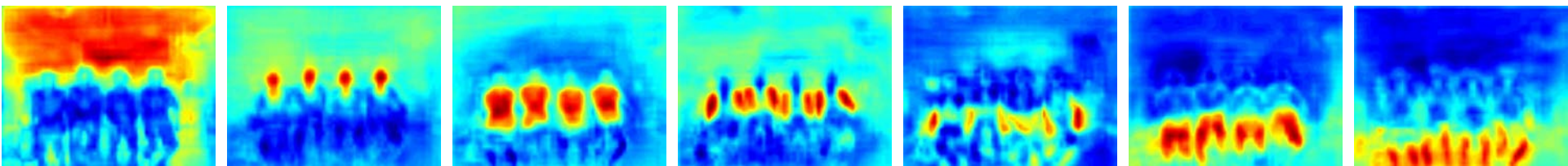
$$\psi_{Global}(V_k = (i, j)) = Q_k(j)$$

for  $(i, j) \in \{1, 2, \dots, D\} \times \{1, 2, \dots, P\} \cup \{0, 0\}$

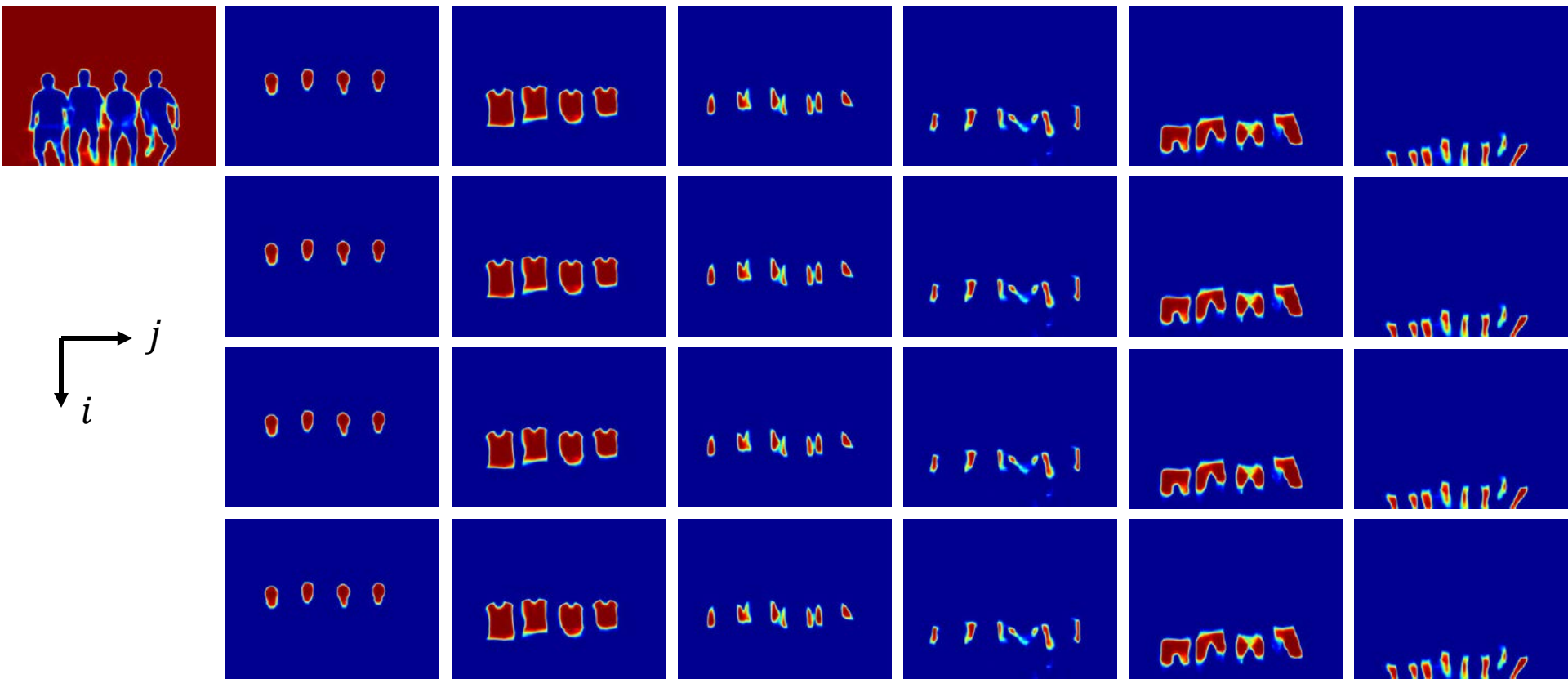
Input 1: Number of human detections

4

Input 2: Semantic body part segmentation probability maps



Output: Global terms



## 2.2 Methodology: Loss function

- Observation: permuting the label IDs in an instance segmentation ground truth produces an equally valid ground truth.



Figure 1. Permutations of ground truth labels are equally valid

## 2.2 Methodology: Loss function

- We match ground truth  $\mathcal{Y}$  to prediction  $\mathcal{P}$  before we carry out loss calculation.
- Matched ground truth is given by:
$$\mathcal{Y}^* = \operatorname{argmax}_{\mathcal{Z} \in \pi(\mathcal{Y})} \operatorname{IoU}(\mathcal{Z}, \mathcal{P})$$
- Then cross-entropy loss is calculated as per normal



(a) Prediction

(a) Matched GT

(a) Ground Truth

Figure 2. Ground truth is matched to our prediction before calculating loss

## 2.3 Methodology:

Obtaining segmentation at other granularities

For each pixel we predict part instance label  
 $(i, j)$   
i.e. part  $j$  of person  $i$



$(i)$   
Instance segmentation of human



$(j)$   
Semantic segmentation of body parts

# 3.1 Results:

## Part instance segmentation

Method	IoU Threshold			$AP_{vol}^r$
	0.5	0.6	0.7	
MNC	38.8	28.1	<b>19.3</b>	36.7
Ours, piecewise, box term only	38.0	27.4	16.7	36.6
Ours, piecewise	38.8	28.5	17.6	37.3
Ours, end-to-end	39.0	28.6	17.4	37.7
Ours, piecewise, box term only, OHEM	38.7	28.9	17.5	36.7
Ours, piecewise, OHEM	39.7	29.7	18.7	37.4
Ours, end-to-end, OHEM	<b>40.6</b>	<b>30.4</b>	19.1	<b>38.4</b>

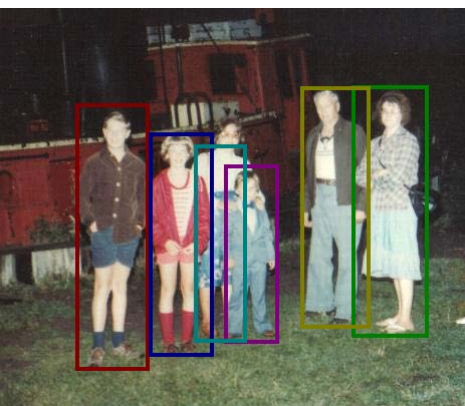
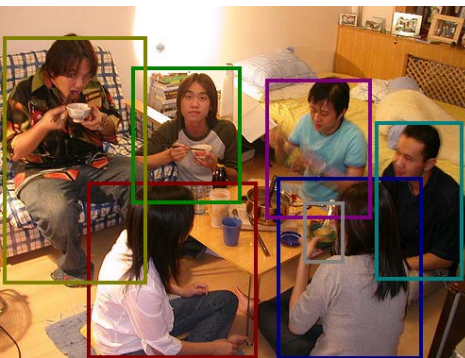
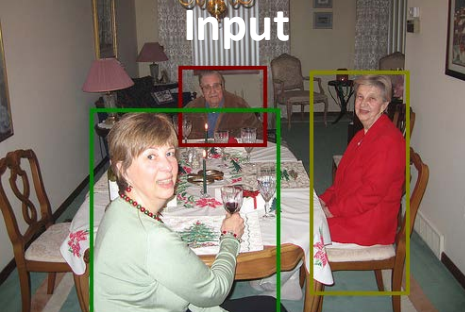
Table 2. Ablation study and comparison of  $AP^r$  at various thresholds to MNC on Pascal Person-Parts test set.  $AP_{vol}^r = \frac{1}{9} \sum_{t=1}^9 AP_{t/10}^r$ .

# 3.1 Results:

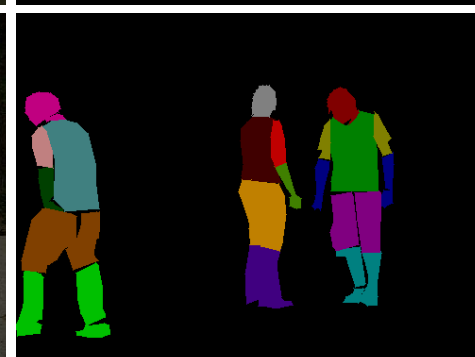
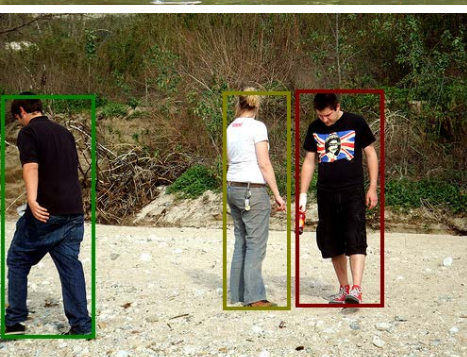
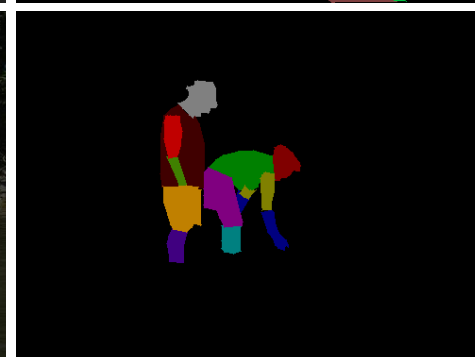
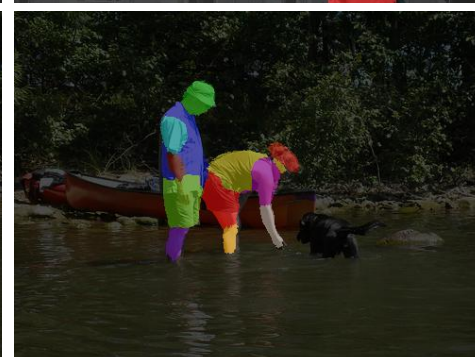
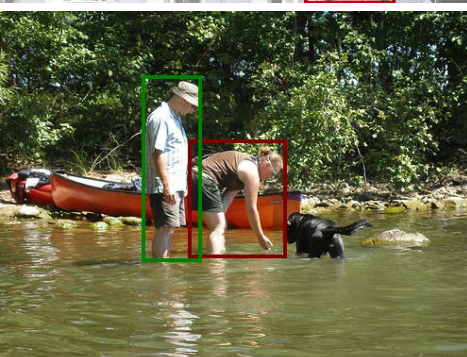
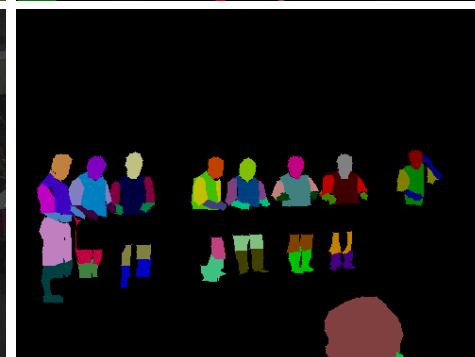
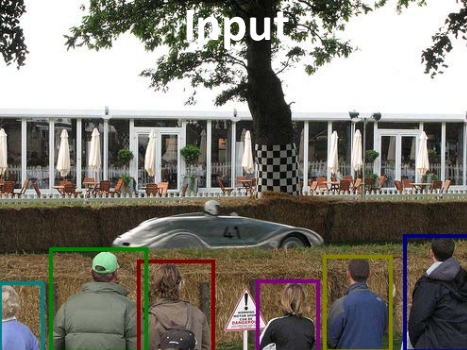
## Part instance segmentation

Success cases...







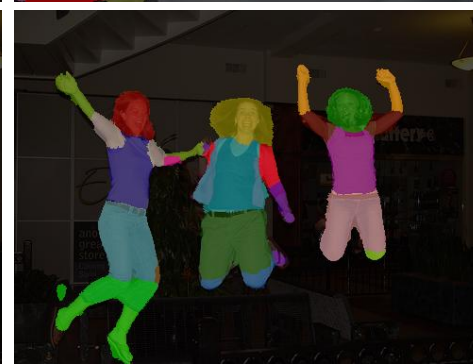
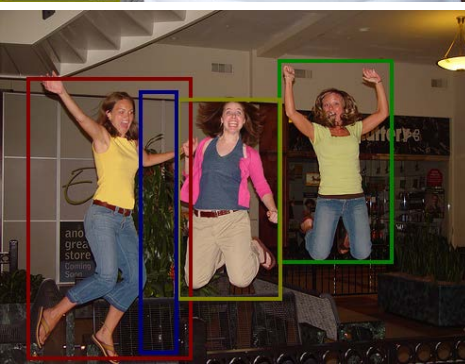
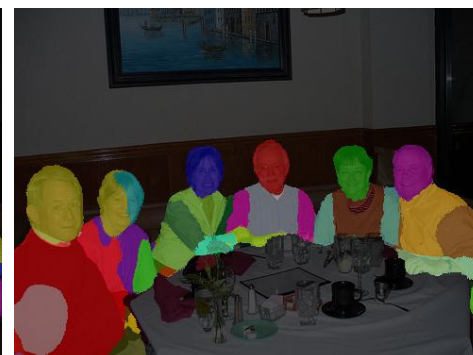
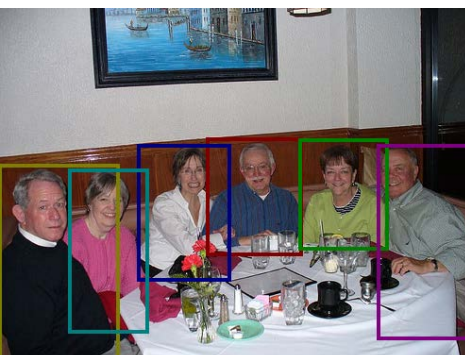
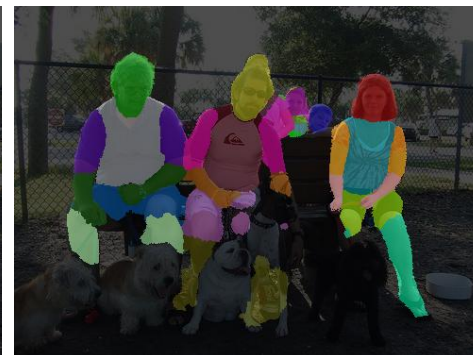
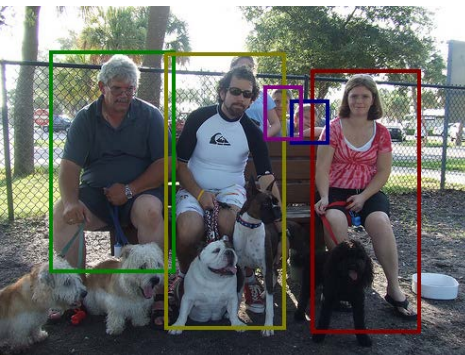
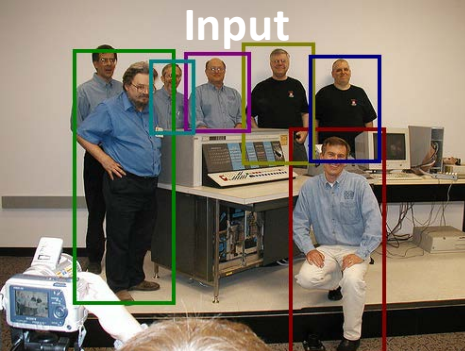


# 3.1 Results:

## Part instance segmentation

Failure cases...



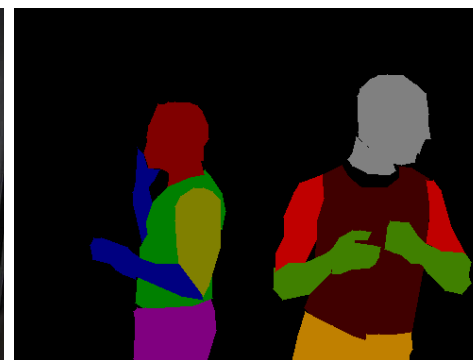
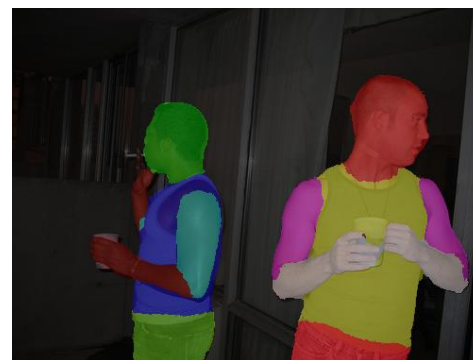
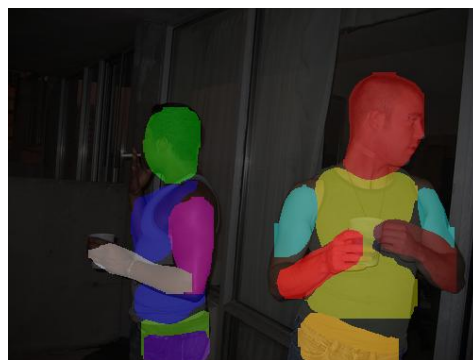
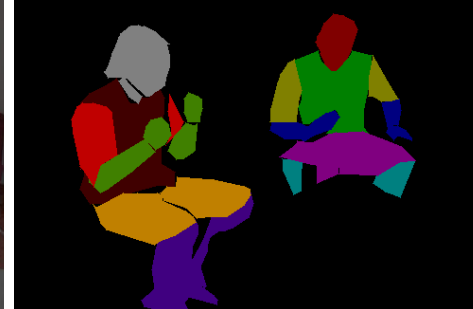


## 3.1 Results:

### Part instance segmentation

Comparison to MNC...



**Input****MNC****Ours****Ground truth**

## 3.2 Results:

# Human instance segmentation

Methods	IoU Thresholds					$AP_{vol}^r$
	0.5	0.6	0.7	0.8	0.9	
SDS	47.9	31.8	15.7	3.3	0.1	-
Chen et al.	48.3	35.6	22.6	6.5	0.6	-
PFN	48.4	38.0	26.5	16.5	5.9	41.3
Arnab et al.	58.6	52.6	41.1	30.4	10.7	51.8
R2-IOS	60.4	51.2	33.2	-	-	-
Arnab et al.	65.6	58.0	46.7	33.0	14.6	57.4
Ours, piecewise	64.0	59.8	51.0	38.3	<b>20.1</b>	57.2
Ours, end-to-end	<b>70.2</b>	<b>63.1</b>	<b>54.1</b>	<b>41.0</b>	19.6	<b>61.0</b>

Table 3. Comparison of  $AP^r$  at various thresholds for instance-level human segmentation on the VOC 2012 validation set.  $AP_{vol}^r = \frac{1}{9} \sum_{t=1}^9 AP_{t/10}^r$ .

## 3.2 Results:

### Human instance segmentation

Comparison to MNC...

(We run the public MNC model on  
Pascal Person-Parts test set)



Input



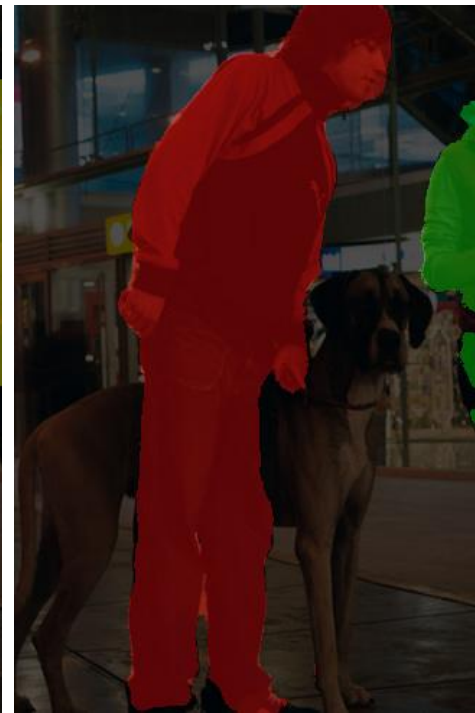
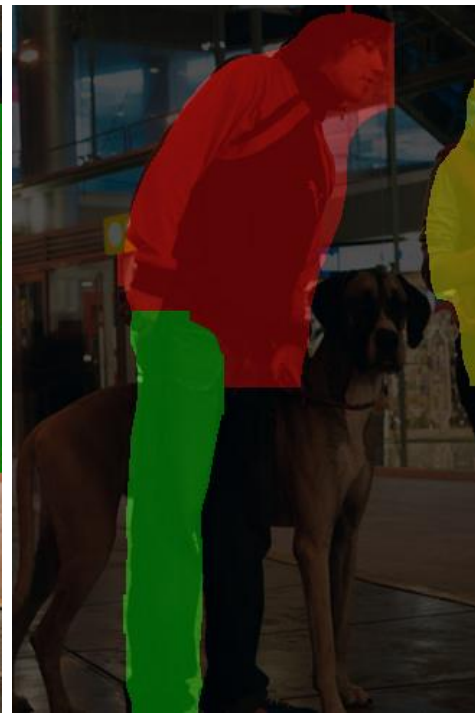
MNC



Ours



Ground truth

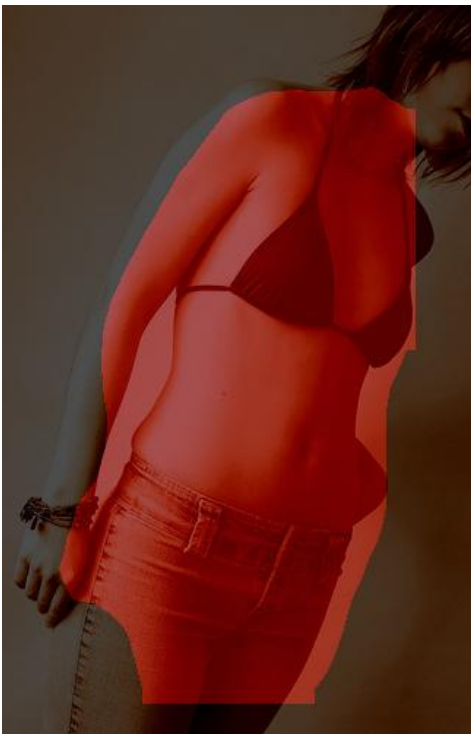




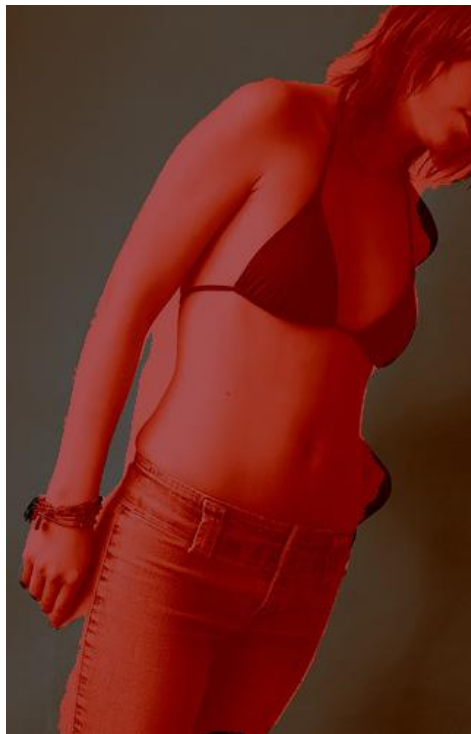
Input



MNC



Ours



Ground truth



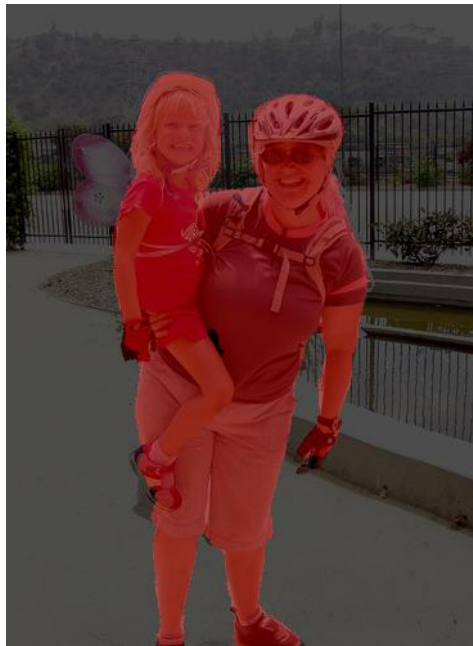
Input



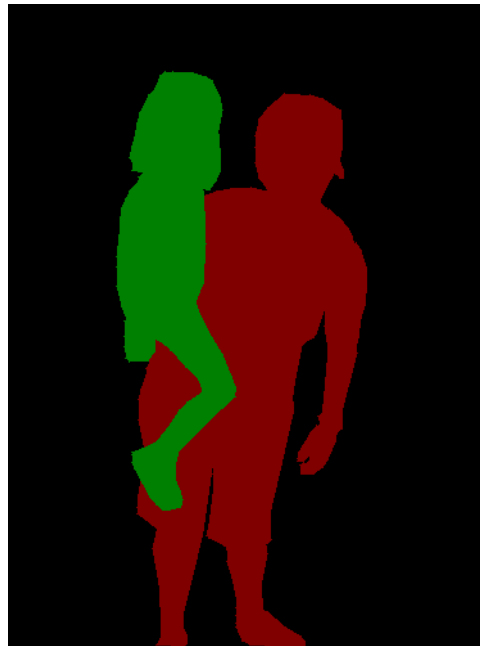
MNC



Ours



Ground truth



## 3.3 Results:

### Semantic segmentation of body parts

Method	IoU [%]
Deeplab	53.0
Attention	56.4
HAZN	57.5
LG-LSTM	58.0
Graph LSTM	60.2
Deeplab-v2	64.9
RefineNet	68.6
Ours, pre-trained	65.9
Ours, final network	66.3

Table 4. Comparison of semantic part segmentation results on the Pascal Person-Parts test set.

# The End

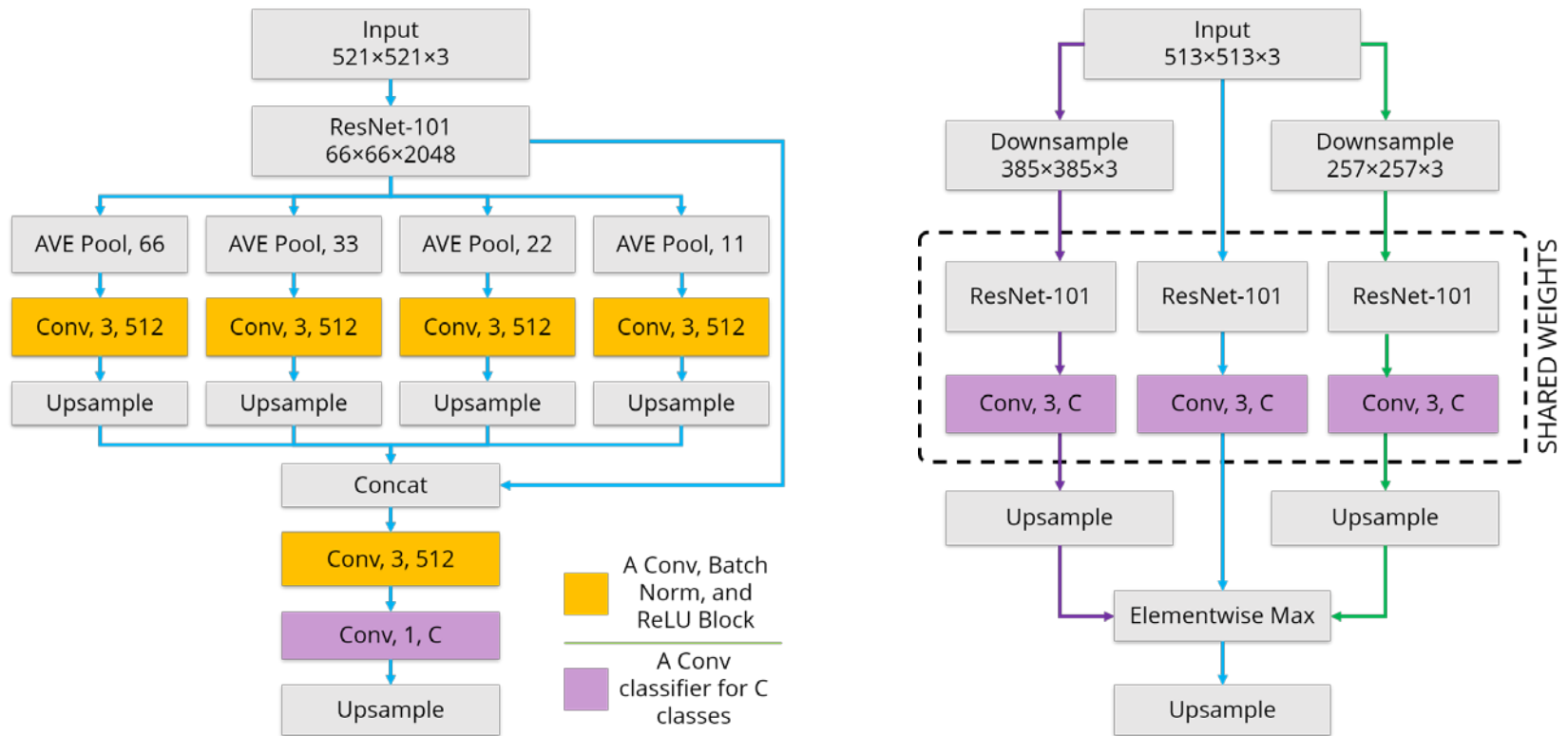


Thank you!

# Appendix



# Methodology: Category-level segmentation module



(a) Ours

(b) Deeplab-v2

Figure 2. Comparison of our category-level segmentation module to Deeplab-v2

# Methodology:

## Category-level segmentation module

	Test IoU [%]	Memory [GB]	Time [s] (fps [ $s^{-1}$ ])
Deeplab-v2	64.4	9.5	0.396 (2.5)
Deeplab-v2+CRF	64.9	11.2	0.960 (1.0)
Ours	65.9	4.3	0.255 (3.9)

Table 1. Comparison of our category-level segmentation module to Deeplab-v2. Tests done on the Pascal Person-Parts dataset. Memory and time requirements are for a single forward pass of the network.

# Experiments

## Training steps:

1. Pretrain the **semantic segmentation network** on all VOC 2012 train and SBD images minus VOC 2012 val and Pascal Person-Parts test to learn the VOC 21 classes.
2. Finetune the model on Pascal Person-Parts training set to predict the 7 body part classes (including the background class).
3. Train a **human detector** on VOC 07+12 trainval images minus VOC 2012 val and Pascal Person-Parts test images. We use the publicly available R-FCN framework.
4. Finetune the **full instance model** end-to-end.



